

PHYS-3202 Homework 11 NOT DUE

This homework is solely for your use in studying and is *not to be handed in*.

1. Rotating Lamina

A rigid lamina (planar object) has principal moments I_1 , I_2 , and $I_3 = I_1 + I_2$ (this is the perpendicular axis theorem that we saw on a previous assignment). The components of the angular velocity along the corresponding principal axes are ω_1 , ω_2 , and ω_3 respectively. Show that $\omega_1^2 + \omega_2^2$ is constant. *Note:* you cannot assume that ω_3 is constant.

2. Finding Principal Axes

Four identical small balls of mass m each are at the following locations in the xy plane: $(x, y, z) = (a, 0, 0), (-a, 0, 0), (a/\sqrt{3}, 2a/\sqrt{3}, 0), (-a/\sqrt{3}, -2a/\sqrt{3}, 0)$. They are held together by very light rods. Treat the balls as idealized point particles and the rods as massless.

- Find the (3D) inertia tensor of this object around the origin.
- Find the principal axes and corresponding moments of inertia for the object.

3. Euler Angles of a Box

In this question, consider a rectangular prism (box) of sides $a \geq b > c$ that rotates as a rigid body. The principle axes \hat{e}_1 , \hat{e}_2 , and \hat{e}_3 are parallel to the sides of length a , b , and c respectively. Initially, \hat{e}_1 , \hat{e}_2 , and \hat{e}_3 are aligned with inertial axes \hat{i} , \hat{j} , and \hat{k} respectively. Choose the correct answer for each part. Explain your answers very briefly. **You may use a small box to visualize the rotations.**

- I rotate the box, so now $\hat{e}_1 = -\hat{k}$, $\hat{e}_2 = \hat{j}$, and $\hat{e}_3 = \hat{i}$. Which Euler angles describe this configuration?
 - $\phi = \pi/2, \theta = 0, \psi = \pi/2$
 - $\phi = \pi/2, \theta = \pi/2, \psi = \pi/2$
 - $\phi = -\pi/2, \theta = -\pi/2, \psi = \pi/2$
 - $\phi = -\pi/2, \theta = \pi/2, \psi = 0$
- I return the box to its initial alignment. Then I rotate it by Euler angles $\phi = \pi$, $\theta = \pi/2$, and $\psi = \pi$. With which inertial axis is \hat{e}_2 aligned?
 - $-\hat{k}$
 - \hat{j}
 - $-\hat{i}$
 - \hat{k}