

PHYS-3202 Homework 9 Due 1 Dec 2021

This homework is due to <https://uwcloud.uwinnipeg.ca/s/wxqoYpEEa8WT2LX> by 10:59PM on the due date. Your file(s) must be in PDF format; they may be black-and-white scans or photographs of hardcopies (all converted to PDF), PDF prepared by LaTeX, or PDF prepared with a word processor *using an equation editor*.

1. Some Eigenvectors *inspired by Riley, Hobson, & Bence and Arfken & Weber*

Define the matrices

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}, \quad C = \begin{bmatrix} 5 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 2 \end{bmatrix}. \quad (1)$$

- (a) By matrix multiplication, show that the vectors $\vec{x} = [1 \ 0 \ -1]^T$, $\vec{y} = [1 \ 1 \ 1]^T$, and $\vec{z} = [1 \ -2 \ 1]^T$ are eigenvectors of both A and B and find their eigenvalues for each matrix.
- (b) Find an orthonormal basis of eigenvectors for C . *Hint:* If you choose carefully, you can find the eigenvectors to be orthogonal from the start. Otherwise, you may need to use the Gram-Schmidt process to orthonormalize your initial choice (you can find the Gram Schmidt process in a mathematical physics textbook if necessary).

2. Some Moments of Inertia

Calculate the moment of inertia of each of the following objects through the specified axis.

- (a) A solid sphere with total mass M and radius R and uniform density about any axis through its center of mass.
- (b) A uniform circular disk of mass M , radius R , and negligible thickness about the axis perpendicular to the disk through the center of mass.

3. Finding Principal Axes

Four identical small balls of mass m each are at the following locations in the xy plane: $(x, y, z) = (a, 0, 0), (-a, 0, 0), (a/\sqrt{3}, 2a/\sqrt{3}, 0), (-a/\sqrt{3}, -2a/\sqrt{3}, 0)$. They are held together by very light rods. Treat the balls as idealized point particles and the rods as massless.

- (a) Find the (3D) inertia tensor of this object around the origin.
- (b) Find the principal axes and corresponding moments of inertia for the object.