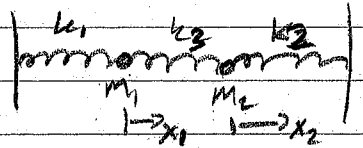


# Coupled Harmonic Oscillators

## ● General Problem + Approaches

- Example: 2 Masses on Springs



• Suppose we have springs of constants  $k_1$  +  $k_2$  attached to 2 walls and 2 masses  $m_1$  +  $m_2$

+ The masses are connected by a 3<sup>rd</sup> spring of constant  $k_3$

+ Measure displacement of each mass by  $x_1, x_2$  from equilibrium position

+ For simplicity, let's take  $m_1 = m_2 = m$ ,  $k_1 = k_2 = k$ ,  $k_3 = \bar{k}$ .

• Equations of motion

+ Excluding a constant, potential energy is

$$V(x_1, x_2) = \frac{1}{2} k (x_1^2 + x_2^2) + \frac{1}{2} \bar{k} (x_2 - x_1)^2$$

so

$$L = \frac{1}{2} m (\dot{x}_1^2 + \dot{x}_2^2) - \frac{1}{2} k (x_1^2 + x_2^2) - \frac{1}{2} \bar{k} (x_2 - x_1)^2$$

+ The EOM are

$$m \ddot{x}_1 + k x_1 + \bar{k} (x_1 - x_2) = 0$$

$$m \ddot{x}_2 + k x_2 + \bar{k} (x_2 - x_1) = 0$$

+ Coupled 2<sup>nd</sup> order ODEs. Different than uncoupled!

• Guess oscillating solution  $x_1 = B_1 e^{i\omega t}$ ,  $x_2 = B_2 e^{i\omega t}$

+ Then we find a matrix eqn

$$\begin{bmatrix} -m\omega^2 + (k + \bar{k}) & -\bar{k} \\ -\bar{k} & -m\omega^2 + (k + \bar{k}) \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} = 0$$

+ Leads to an e-value problem. Characteristic eqn is

$$(k + \bar{k} - m\omega^2)^2 - \bar{k}^2 = 0 \Rightarrow \omega^2 = \frac{1}{m} (k + \bar{k} \pm \bar{k})$$

So there are 2 sol'n's w/ frequencies

$$\omega_1 = \sqrt{(k + 2\bar{k})/m}, \quad \omega_2 = \sqrt{k/m}$$

+ Solution of freq  $\omega_1$  has  $B_1 = -B_2$

while freq  $\omega_2$  sol'n has  $B_1 = B_2$

This means the higher freq  $\omega_1$  sol'n is

antisymmetric motion while the lower freq is symmetric

$$\left[ \begin{array}{c} \rightarrow \\ \leftarrow \\ \rightarrow \\ \leftarrow \end{array} \right] \text{ vs } \left[ \begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \end{array} \right]$$

The symmetric mode does not stretch the  $k$  spring  
 + The general solution is

$$x_1 = A_1 e^{i(\omega_1 t + \theta_1)} + A_2 e^{i(\omega_2 t + \theta_2)}, \quad x_2 = -A_1 e^{i(\omega_1 t + \theta_1)} + A_2 e^{i(\omega_2 t + \theta_2)}$$

or, taking the real part

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} \cos(\omega_1 t + \theta_1) + A_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cos(\omega_2 t + \theta_2)$$

- Small Deviations from Equilibrium: Oscillates Everywhere

• Consider a general Lagrangian

$$L = T(q, \dot{q}) - V(q)$$

+ Suppose there is an equilibrium point where  $q_i = q_i^{(0)}$ . In other words, this is a time-indep. solution of EOM.

+ We want to understand motion close to the equilibrium. Take  $q_i = q_i^{(0)} + \delta q_i(t)$  and expand the Lagrangian in powers of  $\delta q$ .

+ Kinetic energy is generally

$$T = \frac{1}{2} \sum_{ij} T_{ij}(q) \dot{q}_i \dot{q}_j = \frac{1}{2} \sum_{ij} T_{ij}(q^{(0)} + \delta q) \delta \dot{q}_i \delta \dot{q}_j$$

$$= \frac{1}{2} \sum_{ij} (m_{ij} \delta \dot{q}_i \delta \dot{q}_j + \dots) \approx \frac{1}{2} \sum_{ij} m_{ij} \delta \dot{q}_i \delta \dot{q}_j$$

where

$$m_{ij} \equiv T_{ij}(q^{(0)}) = \text{constant mass matrix}$$

+ Meanwhile, potential energy is

$$V(q) = V(q^{(0)}) + \sum_i \frac{\partial V}{\partial q_i}(q^{(0)}) \delta q_i + \frac{1}{2} \sum_{ij} \frac{\partial^2 V}{\partial q_i \partial q_j}(q^{(0)}) \delta q_i \delta q_j + \dots$$

The 1st term is constant (irrelevant).

The 2nd term vanishes b/c force must = 0 at equilibrium  
 So

$$V(q) \approx \frac{1}{2} \sum_{ij} V_{ij} \delta q_i \delta q_j \quad \text{w/ } V_{ij} = \text{Hessian of 2nd derivatives}$$

+ To 2nd order,  $L = \frac{1}{2} \sum_{ij} (m_{ij} \delta q_i \delta q_j - V_{ij} \delta q_i \delta q_j)$

From now on we'll rename  $\delta q \rightarrow q$  for simplicity

+ EOM are

$$\sum_j m_{ij} \ddot{q}_j + \sum_j V_{ij} q_j = 0$$

If you choose linear combinations correctly, you can

$$\ddot{q} + k_{11} q_1 + k_{12} q_2 + \dots = 0$$

This is the same as the coupled spring example.

• Example: Double Pendulum

+ Consider a simple pendulum of mass  $m_2$

length  $l_2$  hanging from a simple pendulum

of mass  $m_1$ , length  $l_1$ . Each has angle  $\theta_1, \theta_2$  from vertical

+ The positions are

$$x_1 = l_1 \sin \theta_1, \quad y_1 = -l_1 \cos \theta_1 \quad (\text{relative to top support})$$

$$x_2 = x_1 + l_2 \sin \theta_2, \quad y_2 = y_1 - l_2 \cos \theta_2$$

so

$$L = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2 l_1 l_2 \cos(\theta_1 - \theta_2) \dot{\theta}_1 \dot{\theta}_2] + m_1 g l_1 \cos \theta_1 + m_2 g l_1 \cos \theta_1 + m_2 g l_2 \cos \theta_2$$

+ Expanding out,

$$L = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 (l_1 \dot{\theta}_1 + l_2 \dot{\theta}_2)^2 - \frac{1}{2} (m_1 l_1 + m_2 l_1) g \theta_1^2 - \frac{1}{2} m_2 l_2 g \theta_2^2$$

+ EOM are

$$(m_1 + m_2) l_1 \ddot{\theta}_1 + m_2 l_2 \ddot{\theta}_2 + (m_1 l_1 + m_2 l_1) g \theta_1 = 0$$

$$m_2 l_2 \ddot{\theta}_1 + m_2 l_2 \ddot{\theta}_2 + m_2 l_2 g \theta_2 = 0$$

- Normal Modes: Solving at level of EOM

• We expect oscillatory solutions, + we look for solutions where all coordinates  $q_i$  oscillate w/ the same frequency, or  $q_i = B_i e^{i\omega t}$  for complex constants  $B_i$

+ These are normal modes.

+ A general solution is a superposition of normal modes b/c the EOM are linear

• Generalized eigenvalue problem

+ Write our guessed solution as

$$\begin{bmatrix} q_1 \\ q_2 \\ \vdots \\ q_n \end{bmatrix} = \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{bmatrix} e^{i\omega t}$$

+ The EOM becomes the matrix eqn

$$-\omega^2 \begin{bmatrix} M_{ij} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_n \end{bmatrix} = - \begin{bmatrix} V_{ij} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_n \end{bmatrix}$$

This is a generalized version of the e' value / e' vector problem

+ To find eigenvalues / normal mode frequencies, note

$$\det(V - M\omega^2) = 0 \quad \text{with } V, M = \text{matrices}$$

Since  $V$  and  $M$  are real symmetric, each e' value  $\omega^2$  is real.

+ Oscillatory normal modes have  $\omega_n^2 > 0$ ;

If  $\omega^2 < 0$ , the solution is a real exponential, meaning the equilibrium is unstable (rolling off a hill)

+ Given an (real) oscillatory frequency  $\omega_n$ , the normal modes are given by solving the vector eqn

$$\omega_n^2 M \vec{\beta}_n = V \vec{\beta}_n$$

+ If  $\beta_{i(n)} = A_{i(n)} e^{i\theta_{i(n)}}$ , general (real) solution is

$$q_i(t) = \sum_n A_{i(n)} \cos(\omega_n t + \theta_{i(n)})$$

n terms of the normal modes

• Normal Coordinates

+ We can show that the normal modes are orthogonal

$$\text{w/ generalized inner product} \quad \begin{bmatrix} m_1 & m_2 & \dots & m_n \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{bmatrix} = 0 \quad \text{if } \omega_p \neq \omega_q$$

This follows b/c

$$\omega_p^2 \vec{\beta}_p^T M \vec{\beta}_q = \vec{\beta}_p^T V \vec{\beta}_q = \omega_q^2 \vec{\beta}_p^T M \vec{\beta}_q$$

So if  $\omega_p \neq \omega_q$  (for different frequencies),

(with degeneracy,  $\omega_p = \omega_q$ ), we can use Gram-Schmidt

+ We can also normalize to  $\vec{\beta}_p^T M \vec{\beta}_q = \delta_{pq}$ .

Then we can write coords w/ an extra amplitude

$$q_i = \sum_n \alpha_n \beta_{i(n)} e^{i\omega_n t} \equiv q_i = \sum_n \beta_{i(n)} \eta_n(t)$$

The  $\eta_n(t)$  variables are normal coordinates. They oscillate with only one frequency

### - Normal Coordinates Directly (in Lagrangian)

Let's work w/o using EOM.

• We can start with kinetic energy.  $T = \frac{1}{2} \sum_{ij} m_{ij} \dot{q}_i \dot{q}_j$   
 + Want to write it as the form

$$T = \frac{1}{2} M_1 \dot{q}_1^2 + \frac{1}{2} M_2 \dot{q}_2^2 + \dots$$

+ Sometimes we can work out the relation of  $q \rightarrow \tilde{q}$  by inspection or term by term

+ More generally, we want to diagonalize  $[m_{ij}]$  which will have eigenvalues  $M_a$

+ Normalize the eigenvectors  $\vec{B}_a$  usually as  $\vec{B}_a^T \vec{B}_b = \delta_{ab}$

$$\text{Then } \tilde{q}_a = \vec{B}_a^T q_i$$

+ Finally, define  $\tilde{\eta}_a = \sqrt{M_a} \tilde{q}_a$ , so

$$T = \frac{1}{2} \sum_a \dot{\tilde{\eta}}_a^2$$

• Next, redefine the potential in terms of  $\tilde{\eta}$  variables

$$+ \text{ We get } V = \frac{1}{2} \sum_{ij} V_{ij} q_i q_j = \frac{1}{2} \sum_{ab} k_{ab} \tilde{\eta}_a \tilde{\eta}_b$$

+ You may be able to do this already in expanding the full potential

+ Now diagonalize  $[k_{ab}]$ . Eigenvalues are  $\omega_n^2$  and eigenvectors  $\vec{B}_a(n)$ . Normalize s.t.  $\vec{B}_a(n)^T \vec{B}_b(n) = \delta_{ab}$

+ Finally define normal coordinates

$$\eta_n = B_a(n) \tilde{\eta}_a,$$

$$\text{so } V = \frac{1}{2} \sum_n \omega_n^2 \eta_n^2$$

• Since  $\vec{B}_a(n)$  are orthonormal, the form of the kinetic energy is unchanged

$$L = \frac{1}{2} \sum_n \dot{\eta}_n^2 - \frac{1}{2} \sum_n \omega_n^2 \eta_n^2$$

The  $\eta_n$  are the normal coordinates

## - Examples

- Revisit our 2 masses on 3 springs  
+ we found a solution

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{i(\omega_1 t + \theta_1)} + A_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{i(\omega_2 t + \theta_2)}$$

- + With normalization, these vectors give normal mode eigenvectors

$$B_{(1)} = \frac{1}{\sqrt{2m}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad B_{(2)} = \frac{1}{\sqrt{2m}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- + The normal coordinates are therefore

$$x_1 = \frac{1}{\sqrt{2m}} (\eta_1 + \eta_2), \quad x_2 = \frac{1}{\sqrt{2m}} (\eta_2 - \eta_1)$$

$$\eta_1 = \sqrt{\frac{m}{2}} (x_1 + x_2), \quad \eta_2 = \sqrt{\frac{m}{2}} (x_1 - x_2)$$

- + We can see that

$$L = \frac{1}{2} m (\dot{x}_1^2 + \dot{x}_2^2) - \frac{1}{2} k (x_1^2 + x_2^2) - \frac{1}{2} k (x_2 - x_1)^2$$

$$= \frac{1}{2} \dot{\eta}_1^2 + \frac{1}{2} \dot{\eta}_2^2 - \frac{1}{2} \left( \frac{k+2k}{m} \right) \eta_1^2 - \frac{1}{2} \frac{k}{m} \eta_2^2$$

- + This follows the 1st approach + confirms the normal mode frequencies in the Lagrangian

- Double pendulum again

- + In terms of the angles,

$$L = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 (l_1 \dot{\theta}_1 + l_2 \dot{\theta}_2)^2 - \frac{1}{2} (m_1 l_1 + m_2 l_1) g \theta_1^2 - \frac{1}{2} m_2 l_2 g \theta_2^2$$

- + Now we can define

$$\tilde{\eta}_1 = \sqrt{m_1} l_1 \theta_1, \quad \tilde{\eta}_2 = \sqrt{m_2} (l_1 \theta_1 + l_2 \theta_2)$$

so

$$L = \frac{1}{2} \dot{\tilde{\eta}}_1^2 + \frac{1}{2} \dot{\tilde{\eta}}_2^2 + \frac{1}{2} \frac{m_1 + m_2}{m_1 l_1} g \tilde{\eta}_1^2 - \frac{1}{2} \frac{g}{l_2} \left( \tilde{\eta}_2 - \sqrt{\frac{m_2}{m_1}} \tilde{\eta}_1 \right)^2$$

- + The potential matrix is

$$[k] = g \begin{bmatrix} \frac{m_1 + m_2}{m_1 l_1} + \frac{m_2}{m_1 l_2} & -\sqrt{\frac{m_2}{m_1}} \frac{1}{l_2} \\ -\sqrt{\frac{m_2}{m_1}} \frac{1}{l_2} & 1/l_2 \end{bmatrix}$$

with  $\tilde{\eta}_1 = \sqrt{m_1} l_1 \theta_1$ ,  $\tilde{\eta}_2 = \sqrt{m_2} (l_1 \theta_1 + l_2 \theta_2)$   
+ we have  $\tilde{\eta}_1 = \sqrt{m_1} l_1 \theta_1$

+ For  $m_1 \gg m_2$ , the frequencies + normal modes are approx (unnormalized)

$$\omega_1^2 \approx g/l_1, \quad \begin{bmatrix} \tilde{\eta}_1 \\ \tilde{\eta}_2 \end{bmatrix} \approx \begin{bmatrix} 1 \\ \sqrt{\frac{m_2}{m_1}} \frac{l_1 - l_2}{l_1} \end{bmatrix} \Rightarrow \frac{\tilde{\eta}_1}{\tilde{\eta}_2} \approx \frac{l_1 - l_2}{l_1} = O(1)$$

and

$$\omega_2^2 \approx g/l_2, \quad \begin{bmatrix} \tilde{\eta}_1 \\ \tilde{\eta}_2 \end{bmatrix} \approx \begin{bmatrix} \sqrt{\frac{m_2}{m_1}} \frac{l_1}{l_2 - l_1} \\ 1 \end{bmatrix} \Rightarrow \frac{\tilde{\eta}_1}{\tilde{\eta}_2} \approx \frac{m_2}{m_1} \frac{l_1}{l_2 - l_1} \ll 1$$

In the 2nd, this is almost the lower pendulum swinging with the upper stationary. (May see other extreme on HW)

### - Weak Coupling + Forcing

• Weak coupling is the case that we have basically 2 separate oscillators that affect each other just a little.

• Let's go back to our 3 spring prototype example, first with all springs different but  $m_1 = m_2 = m$

+ We have the Lagrangian problem

$$L = \frac{1}{2} m (\dot{x}_1^2 + \dot{x}_2^2) - \frac{1}{2} k_1 x_1^2 - \frac{1}{2} k_2 x_2^2 - \frac{1}{2} k (x_2 - x_1)^2$$

$$m \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} k_1 + k & -k \\ -k & k_2 + k \end{bmatrix} \quad \text{with } k \ll k_1, k_2$$

+ The characteristic eqn is

$$\det \begin{bmatrix} k_1 + k - m\omega^2 & -k \\ -k & k_2 + k - m\omega^2 \end{bmatrix} \approx (m\omega^2 - k_1)(m\omega^2 - k_2) \mp 11 = 0$$

The frequencies are  $\omega_{(1)} \approx \sqrt{k_1/m}$ ,  $\omega_{(2)} \approx \sqrt{k_2/m}$

+ In each case, (unnormalized) normal mode vectors are

$$\approx \begin{bmatrix} 1 \\ k/(k_2 - k_1) \end{bmatrix} \quad \text{and} \quad \approx \begin{bmatrix} k/(k_1 - k_2) \\ 1 \end{bmatrix} \quad \text{Note these are}$$

+ These are almost just motion of  $x_1$  +  $x_2$  clearly

+ Suppose we have initial conditions  $x_1 = a$ ,  $x_2 = 0$ ,  $\dot{x}_1 = \dot{x}_2 = 0$   
Then

$$x_1 = a \cos(\omega_1 t) + \dots$$

$$x_2 = a k / (k_2 - k_1) [\cos(\omega_1 t) - \cos(\omega_2 t)] + \dots$$

This is large amplitude motion of  $x_1$  + small of  $x_2$

• But take this example with degeneracy  $k_1 = k_2 = k$ .

+ From before we know

$$\omega_{(1)}^2 = \frac{k + 2k}{m}, \quad \omega_{(2)}^2 = k/m$$

with normal modes  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

+ Given if  $k \ll k_0$ , these normal modes are very different from  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . (This applies if  $k_1, k_2$  but  $k_0 \approx k_1, -k_2$  also)

+ If we take those same initial conditions

$$x_1 = \frac{a}{2} [\cos(\omega_1 t) + \cos(\omega_2 t)]$$

$$x_2 = \frac{a}{2} [\cos(\omega_1 t) - \cos(\omega_2 t)]$$

With trig identities, these are

$$x_1 = a \cos\left[\frac{(\omega_1 + \omega_2)t}{2}\right] \cos\left[\frac{(\omega_1 - \omega_2)t}{2}\right]$$

$$x_2 = a \sin\left[\frac{(\omega_1 + \omega_2)t}{2}\right] \sin\left[\frac{(\omega_1 - \omega_2)t}{2}\right]$$

+ Now we expand in  $k/k_0 = \epsilon$ .

$$\omega_1 + \omega_2 \approx \sqrt{2k/m}, \quad \omega_1 - \omega_2 \approx \epsilon \sqrt{k/m}$$

Therefore

$$x_1 = a \cos(\epsilon \omega_2 t / 2) \cos(\omega_1 t), \quad x_2 = a \sin(\epsilon \omega_2 t / 2) \sin(\omega_1 t)$$

where  $\omega_1$  = freq of the uncoupled oscillator.

+ These are oscillations  $90^\circ$  out of phase with freq = single oscillator freq, and an amplitude envelope with a frequency = beat frequency.

• Forcing may apply at weak or strong coupling

+ It's usually easiest to write this in terms of normal coordinates b/c they have definite frequencies

+ So take our degenerate 3-spring example. Recall

$$\eta_1 = \frac{1}{\sqrt{2}}(x_1 - x_2), \quad \eta_2 = \frac{1}{\sqrt{2}}(x_1 + x_2)$$

+ If a force acts on the 1<sup>st</sup> mass, the EOM are

$$m\ddot{x}_1 + \dots = F(t), \quad m\ddot{x}_2 + \dots = 0$$

$$\Rightarrow \ddot{\eta}_1 + \omega_1^2 \eta_1 = F(t)/\sqrt{2}m, \quad \ddot{\eta}_2 + \omega_2^2 \eta_2 = F(t)/\sqrt{2}m$$

Solve each as usual, add back to get  $x_1, x_2$

+ Of course you can change forcing, apply to nondegenerate oscillators, etc.