# PHYS-2106 Winter Homework 4 Due 6 Feb 2017

This homework is due in the dropbox outside 2L26 by 10:59PM on the due date. You may alternately email a PDF (typed or black-and-white scanned) or give a hardcopy to Dr. Frey.

#### 1. Inverses and Systems of Equations

- (a) Carry out the *LU* decomposition (as defined in class and the reading) of the 2 × 2 matrix  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and then use that decomposition to verify that  $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$
- (b) inspired Kreyszig Solve the system of equations Ax = b for

$$A = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -4 & 1 \end{bmatrix} \text{ and } b = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix}.$$
 (1)

#### 2. Pauli Matrices Again

Recall from our previous assignment that the Pauli matrices are defined by

$$\sigma_x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad \sigma_y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \quad \sigma_z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$
(2)

- (a) Show that the Pauli matrices are Hermitian.
- (b) Show that the Pauli matrices are unitary.
- (c) Find the eigenvalues and eigenvectors for all three Pauli matrices. Normalize the eigenvectors so that their norms are equal to one.

#### 3. Eigenvectors of a Degenerate Eigenvalue

Suppose a matrix A has two linearly independent eigenvectors x and y with the same eigenvalue  $\lambda$ . Show that any linear combination ax + by (with a, b any scalars) is also an eigenvector of A with eigenvalue  $\lambda$ .

### 4. Moment of Inertia Tensor partly from Boas, partly from Marion & Thornton

The angular velocity  $\vec{\omega}$  and angular momentum  $\vec{L}$  of a rotating object are generally related by the linear equation  $\vec{L} = I\vec{\omega}$ , where I is a 3 × 3 matrix called the *moment of inertia tensor* of the object.

(a) The eigenvectors of I are called the principal axes, and the corresponding eigenvalues  $I_1, I_2, I_3$  are the principal moments of inertia. Argue that  $\vec{L}$  and  $\vec{\omega}$  are parallel if and only if  $\vec{\omega}$  lies along a principal axis.

Suppose a cube of side b and uniform density with total mass M is aligned along the x, y, z axes with one corner at the origin. Its moment of inertia tensor is

$$I = Mb^{2} \begin{bmatrix} \frac{2}{3} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{2}{3} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{2}{3} \end{bmatrix} .$$
(3)

- (b) If the cube is rotating around the x axis with angular velocity  $\vec{\omega} = \begin{bmatrix} \omega & 0 & 0 \end{bmatrix}^T$ , find the angular momentum.
- (c) Find the principal moments of the cube. You may use Maple to calculate any determinants or solve the characteristic equation (using the solve command), but you must attach a printout of your Maple worksheet in that case.

## 5. Practice Problems (NOT GRADED)

For your own practice, the following problems from the course textbooks are useful (and mostly have solutions in the texts):

- RHB chapter 8 problems 1,3,7(a,b,c),17,33
- Spiegel chapter 15 supplementary problems 49,63,76,82,83,89,90,96(a,b)