

PHYS-4601 Homework 4 Due 8 Oct 2015

This homework is due in the dropbox outside 2L26 by 11:59PM on the due date. You may alternately email a PDF (typed or black-and-white scanned) or give a hardcopy to Dr. Frey.

1. Gaussian Wavepacket Part I

Here we take a first look at the Gaussian wavepacket in 1D, which is an important state in more than one physical system. In this problem, we will consider the state at a single instant $t = 0$, ignoring its time evolution. The state is

$$|\psi\rangle = \int_{-\infty}^{\infty} dx A e^{-ax^2} |x\rangle . \quad (1)$$

- Find the normalization constant A . *Hint:* To integrate a Gaussian, consider its square. When you square it, change the dummy integration variable to y , then change the integral over $dx dy$ to plane polar coordinates.
- Since the wavefunction is even, $\langle x \rangle = 0$. Find $\langle x^2 \rangle$. *Hint:* You can get a factor of x^2 next to the Gaussian by differentiating it with respect to the parameter a .
- Write $|\psi\rangle$ in the momentum basis. *Hint:* If you have a quantity $ax^2 + bx$ somewhere, you may find it useful to write it as $a(x + b/2a)^2 - b^2/4a$ by completing the square. Then shift integration variables so it looks like you have a Gaussian again.
- Find $\langle p \rangle$ and $\langle p^2 \rangle$ and show that this state saturates the Heisenberg uncertainty principle.

2. The Virial Theorem Based on Griffiths 3.31

Consider 3D quantum mechanics.

- Using Ehrenfest's theorem, show that

$$\frac{d}{dt} \langle \vec{x} \cdot \vec{p} \rangle = \left\langle \frac{\vec{p}^2}{m} \right\rangle - \langle \vec{x} \cdot \vec{\nabla} V(\vec{x}) \rangle . \quad (2)$$

- Show that the left-hand side of (2) vanishes in a stationary state to prove the *virial theorem*

$$2\langle K \rangle = \langle \vec{x} \cdot \vec{\nabla} V(\vec{x}) \rangle , \quad (3)$$

where K is the kinetic energy. (The virial theorem holds classically, also, though without the expectation values.)

- Using the virial theorem, find the ratio of (the expectation value of) the kinetic energy to the potential energy for the harmonic oscillator potential $V \propto \vec{x}^2$ and for the Coulomb potential $V \propto 1/|\vec{x}|$. *Hint:* Remember from electromagnetism (or Newton's law of gravity) that $\vec{\nabla}(1/|\vec{x}|) = -\vec{x}/|\vec{x}|^3$.

3. Measurement vs Time Evolution a considerable expansion of Griffiths 3.27

Suppose a system has observable A with eigenstates $|a_1\rangle, |a_2\rangle$ of eigenvalues a_1, a_2 respectively and Hamiltonian H with eigenstates $|E_1\rangle, |E_2\rangle$ of energies E_1, E_2 respectively. The eigenstates are related by

$$|a_1\rangle = \frac{1}{5} (3|E_1\rangle + 4|E_2\rangle) , \quad |a_2\rangle = \frac{1}{5} (4|E_1\rangle - 3|E_2\rangle) . \quad (4)$$

Suppose the system is measured to have value a_1 for A initially. Each of the following parts asks about a different possible set of subsequent measurements.

- (a) What is the probability of measuring energy E_1 immediately after the first measurement? Assuming we do get E_1 , what is the probability of measuring a_1 again if we measure A again immediately after the measurement of energy?
- (b) Instead, consider immediately measuring A again after the first measurement. What are the probabilities for observing a_1 and a_2 ?
- (c) Finally, consider making the first measurement and then allowing the system to evolve for time t . If we then measure energy, what is the probability of finding energy E_1 ? If we instead measured A again, what is the probability we find a_1 again?