

Formalism

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• Postulate 1 + Vector Spaces

States in QM are unit norm vectors in complex vector spaces with an inner product

→ What do we mean by a complex vector space? It is a set of vectors \vec{x}, \vec{y} ,

1) closed under addition $\vec{x} + \vec{y}$ is a vector
Addition is commutative and associative

2) There is a zero vector $\vec{0}$ st. $\vec{x} + \vec{0} = \vec{x}$
and an inverse for each vector $\vec{x} + (-\vec{x}) = \vec{0}$

3) closed under multiplication by complex scalars (numbers)
 $c\vec{x}$ is a vector

Multiplication is distributive + associative

Multiplication by 0 gives $\vec{0}$ and by 1 the vector $1 \cdot \vec{x} = \vec{x}$.

Example A set of column matrices

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

This has basis $\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots$ ← smallest set of vectors whose linear combination spans the space

There may be many bases; the vector may be written in terms of any basis

Dimension = # of basis vectors

$$\vec{x} = x_1 \vec{e}_1 + x_2 \vec{e}_2 + \dots + x_n \vec{e}_n \quad \text{or} \quad \vec{x} = x'_1 \vec{e}'_1 + \dots + x'_n \vec{e}'_n$$

← components

→ An inner product takes 2 vectors + gives a complex scalar $\langle \vec{x}, \vec{y} \rangle$.

1) Linear in right-hand argument $\langle \vec{x}, a\vec{y} + b\vec{z} \rangle = a\langle \vec{x}, \vec{y} \rangle + b\langle \vec{x}, \vec{z} \rangle$

2) Anti-linear in left-hand argument $\langle a\vec{x} + b\vec{y}, \vec{z} \rangle = a^* \langle \vec{x}, \vec{z} \rangle + b^* \langle \vec{y}, \vec{z} \rangle$
Equivalently $\langle \vec{x}, \vec{y} \rangle = \langle \vec{y}, \vec{x} \rangle^*$

3) Positive Semi-definite $\langle \vec{x}, \vec{x} \rangle \geq 0$ and equals only if $\vec{x} = \vec{0}$.

It allows us to define a norm $|\vec{x}| = \sqrt{\langle \vec{x}, \vec{x} \rangle}$
Orthogonal vectors have $\langle \vec{x}, \vec{y} \rangle = 0$.

Example

For an n -dimensional example, $\langle \vec{x}, \vec{y} \rangle = x_1^* y_1 + x_2^* y_2 + \dots + x_n^* y_n$
in components if the basis is orthonormal.
Components in orthonormal basis are $x_i = \langle \vec{e}_i, \vec{x} \rangle$. Just a dot product

Postulate 2 + Operators

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Every observable is associated with a linear operator on the vector space of states. This operator is Hermitian, and any measurement gives an eigenvalue.

- A linear operator \hat{O} on the vector space:

1) Takes a vector \vec{x} to a vector \vec{y} : $\vec{y} = \hat{O}\vec{x}$.

2) Is linear: $\hat{O}(ax + by) = a\hat{O}\vec{x} + b\hat{O}\vec{y}$

- The (Hermitian) adjoint of \hat{O} is denoted \hat{O}^\dagger and satisfies

$$\langle \vec{x}, \hat{O}\vec{y} \rangle = \langle \hat{O}^\dagger \vec{x}, \vec{y} \rangle. \text{ A Hermitian operator has } \hat{O}^\dagger = \hat{O}.$$

Ex In any basis, \hat{O} is represented by a matrix multiplying the column

$$\vec{y} = \hat{O}\vec{x} \Rightarrow y_i = \sum_j O_{ij} x_j \quad \text{or } y_i = O_{ij} x_j \text{ repeated index summed (Einstein convention)}$$

$$\text{Since } \langle \vec{x}, \vec{y} \rangle = x_i^* y_i, \quad \langle \vec{x}, \hat{O}\vec{y} \rangle = x_i^* O_{ij} y_j = (x_i^* O_{ij}) y_j$$

$$\text{This shows that } \hat{O}^\dagger = (\hat{O}^*)^T$$

- An eigenvector or eigenstate of \hat{O} is a non-zero vector \vec{x} such that $\hat{O}\vec{x} = \lambda\vec{x}$ for λ a scalar called the eigenvalue.

Ex For a matrix representation, we have

$$(\hat{O} - \lambda\mathbf{I})\vec{x} = 0 \Rightarrow \det(\hat{O} - \lambda\mathbf{I}) = 0$$

This equation gives the eigenvalues (+ the 1st then gives eigenvectors)

- Properties of Hermitian operators

• Eigenvalues are real: for eigenvector \vec{x} , of \hat{O} ,

$$\langle \vec{x}, \hat{O}\vec{x} \rangle = \lambda \langle \vec{x}, \vec{x} \rangle \quad \text{and} \quad \langle \vec{x}, \hat{O}\vec{x} \rangle = \langle \hat{O}^\dagger \vec{x}, \vec{x} \rangle = \langle \hat{O}\vec{x}, \vec{x} \rangle = \lambda^* \langle \vec{x}, \vec{x} \rangle$$

• Eigenvectors with different eigenvalues are orthogonal: $\lambda_1 \neq \lambda_2$

$$\lambda_1 \langle \vec{x}, \vec{y} \rangle = \langle \vec{x}, \hat{O}\vec{y} \rangle = \langle \hat{O}\vec{x}, \vec{y} \rangle = \lambda_2 \langle \vec{x}, \vec{y} \rangle \Rightarrow \langle \vec{x}, \vec{y} \rangle = 0$$

• We will assume (and can sometimes prove) that eigenvectors of a Hermitian operator form a basis (which can be made orthonormal)

Postulate 3

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If a system is in a state represented by a vector \vec{x} , then the probability of measuring the eigenvalue λ of operator \hat{O} with associated eigenvector \vec{y} is $|\langle \vec{y}, \vec{x} \rangle|^2$

- This one is actually sort of self-explanatory. We will see how it relates to our old prescriptions shortly.

• Hilbert Spaces (remember this name)

- Vector spaces do not have to have finite dimensions

We could imagine taking our column matrices & let them extend infinitely

- A Hilbert space is a vector space with an inner product that also includes the limit points of all series in it. • Basically, this extends the closure rule for addition of vectors to convergent infinite sums.

• All the finite dimensional spaces we've talked about are Hilbert spaces

- The Hilbert spaces of interest in physics are called L^2 spaces over a given volume. These are spaces where the vectors are functions that are square-integrable (and therefore normalizable) over the volume

$$f(x) \in L^2 \text{ if } \int_V d^3x |f(x)|^2 < \infty$$

• For example, this could be over all 3D volume or just an interval $a < x < b$ in 1D

• The inner product is just $\langle f(x), g(x) \rangle = \int_V d^3x f^*(x)g(x)$

And this is always finite for L^2 functions

- States & wavefunctions are normalized vectors in Hilbert space.